Direct Numerical Simulation of the Neutrally Stratified Turbulent Ekman Boundary Layer

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Abstract Direct numerical simulations (DNSs) are performed for the turbulent Ekman boundary layer over a smooth surface. The Reynolds numbers \( Re_f \) are set to be \( Re_f = 400, 510, 600, 775, 1140 \) and \( 1393 \) where \( Re_f \) is based on the geostrophic wind \( G \), the kinematic viscosity \( \nu \) and Coriolis parameter \( f \). The simulations of \( Re_f = 1140 \) and \( 1393 \) have been carried out on the Earth Simulator. In the cases of the higher Reynolds numbers, the mean velocity profiles show good agreement with the experimental data of Caldwell et al. (1972) and the DNS data of Coleman (1999). A low-speed large-scale structure is found in the upper region, whereas the well-known streaky structure appears in the vicinity of the wall. This large-scale structure is observed in a motion of a material line. The inclination of this structure does not coincide with the direction of the mean flow velocity. The reason is discussed based upon the motion of a material line whose initial position is horizontal in a vicinity of the wall. In addition, the eddy-viscosity model proposed by Blackadar (1962, 1965) is examined with respect to the obtained DNS data base. The improved model gives good agreement with the results by the present DNS.

Keywords: DNS, Ekman boundary layer, turbulence structure, eddy-viscosity model

1. Introduction

Rotation is one of the factors which affect the planetary boundary layer (PBL). The boundary layer under the effect of the system rotation is called the Ekman boundary layer. The Ekman boundary layer is three-dimensional flow in nature, in which three forces are balanced, i.e., the pressure gradient, viscous and the Coriolis forces.

Many numerical simulations of the turbulent PBL have been performed with the advancement of the computer. One of the major tools in numerical researches on the turbulent PBL is large-eddy simulation (LES) (e.g. Moeng [1], Mason [2], Andrén et al. [3] and Lin et al. [4]), in which the large-scale motions are directly computed while the effect of the unresolved-scale one is approximated by a sub-grid scale model. Another major approach is Reynolds averaged Navier-Stokes equation (RANS) (e.g. Duyunkeke [5] and Andrén [6]), in which mean components are only calculated. One of the advantages of LES and RANS is that flow fields of realistic Reynolds numbers can be calculated. Results from LES and RANS, however, include approximation due to the underlying modeling. We adopt here the technique of another approach, i.e., direct numerical simulation (DNS), all of the relevant scale motions are resolved. Therefore, DNS gives accurate reliable data. In addition, DNS of the turbulent Ekman boundary layer provide fundamental information on the three-dimensional turbulent boundary layer as well as the PBL in order to improve turbulence models in LES and RANS.

Among studies of the Ekman boundary layer, the studies using DNS have barely been performed. Coleman et al. [7] performed DNSs of the turbulent Ekman boundary layer with low Reynolds numbers, and found that no horizontal roll vortices appeared under neutral stratification. Coleman et al. carried out DNSs on buoyantly stable [8] and unstable [9, 10] cases, and obtained horizontal roll vortices only for a moderate wall heating. Later, Coleman [11] conducted DNS of the turbulent Ekman boundary layer with a high Reynolds number of \( Re_f = 1000 \) to estimate universal constants of the classical similarity theory [12, 13]. Here, \( Re_f \) is defined by

\[
Re_f = \frac{GD}{\nu} = \frac{G}{\sqrt{\nu f/2}},
\]

where \( G \) is the geostrophic wind velocity, \( f \) the Coriolis parameter and \( D \) the viscous Ekman layer depth \((=\sqrt{2\nu f})\). Shingai et al. [14] employed a larger com-
putational domain and found that a large turbulent structure in the region where the mean velocity reached its maximum. Shingai et al. [14] also observed the inertial oscillation in the upper region.

In the present study, we calculated DNSs of the neutrally stratified turbulent Ekman boundary layer at the higher Reynolds numbers of $Re_f = 1140$ and 1393, which have been enabled by use of the Earth Simulator. Our objective is to investigate Reynolds number dependence and the three-dimensional characteristics (such as turbulence structures) in the turbulent Ekman boundary layer. The Reynolds number attainable through DNS is, however, still much smaller than those of the actual PBL. The RANS plays an important role in the simulation of the PBL. Accordingly, we evaluate the eddy-viscosity model proposed by Blackadar [15, 16] to improve it based on the present results.

2. Simulated flow and numerical methods

A calculated flow field is the turbulent Ekman boundary layer of an incompressible viscous fluid over a smooth surface. The system is rotating about a vertical axis with an angular velocity $\Omega = (0, 0, f/2)$. The flow is driven by the combination of the horizontal pressure gradient and the Coriolis force. The configuration of the computational domain is given in Figure 1. The periodic boundary conditions are imposed in the streamwise ($x$) and spanwise ($y$) directions. The non-slip condition is adopted on the bottom surface, and the Neumann condition on the upper boundary.

The fundamental equations set are as follows:

$$\nabla \cdot \mathbf{u} = 0,$$

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla)\mathbf{u} + 2\Omega \times \mathbf{u} = -\frac{1}{\rho} \nabla p + \nu \nabla^2 \mathbf{u},$$

where $\rho$ is the fluid density and $p$ the pressure.

The fractional step method is used for the coupling between the continuity and the Navier-Stokes equations. The second-order Crank-Nicolson and the Adams-Bashforth methods are employed as the time advance algorithms; the former for the vertical viscous term and the latter for the other terms. The finite-difference method is applied for the spatial discretization. The fourth-order central difference scheme [17] is adopted in the $x$- and $y$-directions, and the second-order central difference scheme in the wall-normal ($z$) direction.

The non-dimensional parameters are the Reynolds number ($Re$) and the Rossby number ($Ro$) defined by

$$Re = \frac{Gh}{\nu}, \quad Ro = \frac{G}{f h},$$

where $h$ is the height of the computational domain. Our calculations use these non-dimensional numbers as parameters, while those of Coleman et al. [7, 8, 9, 10, 11] used Reynolds number $Re_f$.

The summary of the computational conditions is given in Table 1. Here, $L_x$, $L_y$, and $L_z (= h)$ are the widths of the computational domain and $N_x$, $N_y$, and $N_z$ are the number of grid points in the $x$, $y$, and $z$ directions.

<table>
<thead>
<tr>
<th>$Re_f$</th>
<th>400</th>
<th>510</th>
<th>600</th>
<th>775</th>
<th>1140</th>
<th>1393</th>
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<tbody>
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<td></td>
<td></td>
<td></td>
<td></td>
<td>8000</td>
<td>13000</td>
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<td>$Ro$</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
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<tr>
<td>$L_x$, $L_y$, $L_z$</td>
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<td>102.0D</td>
<td>90.0D</td>
<td>147.2D</td>
<td>57.0D</td>
<td>90.5D</td>
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<tr>
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<td>20.0D</td>
<td>25.5D</td>
<td>30.0D</td>
<td>38.7D</td>
<td>57.0D</td>
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<td>$L_x^+$, $L_y^+$</td>
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<td>1060</td>
<td>1680</td>
<td>3384</td>
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<td>512</td>
<td>512</td>
<td>1024</td>
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<td>160</td>
<td>160</td>
<td>256</td>
<td>512</td>
<td>768</td>
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<td>$\Delta x^+$, $\Delta y^+$</td>
<td>6.11</td>
<td>6.23</td>
<td>6.24</td>
<td>6.25</td>
<td>6.60</td>
<td>6.26</td>
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<tr>
<td>$\Delta z^+$</td>
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<td>0.177–12.5</td>
<td>0.150–18.5</td>
<td>0.147–18.3</td>
<td>0.147–18.4</td>
<td>0.143–17.7</td>
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<tr>
<td>$\Delta z^+$</td>
<td>90.0</td>
<td>43.0</td>
<td>57.0</td>
<td>15.7</td>
<td>23.3</td>
<td>4.3</td>
</tr>
</tbody>
</table>

Fig. 1 Configuration of computational domain.
of grid points in the x-, y- and z-directions, respectively. All variables with the superscript of + are normalized by \(v\) and \(u_\tau\), where \(u_\tau\) is the friction velocity. The computational domains of \(Re_f = 400, 510, 600, 775, 1140\) and 1393 are bigger than the DNSs ever performed. The height of the computational domain is set such that it is large compared with the boundary layer thickness. The grid spacings \(\Delta_x^+, \Delta_y^+\) and \(\Delta_z^+\) are decided based on the DNS of the turbulent Poiseuille flow performed by Abe et al. [18]. They reported that the results obtained by using the horizontal discretizations of \(\Delta_x^+ = 8.00\) and \(\Delta_y^+ = 5.00\) showed good agreement with the experimental data [19] and the results from the DNS with the spectral method [20]. As for the vertical spacing \(\Delta_z^+\), they used the non-uniform mesh in a range 0.15–8.02. In the present simulation, the horizontal grid spacing is almost of the same size as the spanwise spacing of Abe et al. [18], and the minimum value of the vertical spacing is nearly equal to the one used by them. Although the maximum value of the vertical spacing is about twice as large as the one of the Poiseuille flow, this is allowable because of the disappearance of small vortices in the upper region. As for the computational time, the averaging time is not enough in the cases of \(Re_f = 1393\). In this paper, therefore, we will present the data of only instantaneous flow fields with respect to the case of \(Re_f = 1393\).

3. Reynolds number dependence of turbulence statistics

3.1 Mean velocity profile

The absolute values of mean velocity \(Q^+\) as a function of the height \(z^+\) are given in Figure 2 and compared with the experiments of Caldwell et al. [21]. The DNS of turbulent Ekman boundary layer performed by Coleman [11] and the one of the turbulent Poiseuille flow by Abe et al. [18] are also shown for comparison. The absolute velocity \(Q\) is defined as

\[
Q = \sqrt{U^2 + V^2},
\]

where \(U\) and \(V\) are the streamwise and spanwise mean velocity components, respectively. The Reynolds number \(Re_L\) is defined by \(Re_L = GL/\sqrt{\nu \Omega L}\), where \(\Omega L\) is the angular velocity of the plate rotation in the experiments of Caldwell et al. [21]. This Reynolds number is the same Reynolds number as \(Re_f\) by definition. The effect of rotation is only the Coriolis force in the present study, while the centrifugal force also takes place in their experiments. Even if \(Re_f\) is the same value of \(Re_L\), some differences exist between the present study and his experiments. Thus, we use \(Re_f\) in the case of experiment to avoid confusion with our DNSs.

It is well known that the mean velocity follows the logarithmic region in wall turbulence, expressed as

\[
Q^+ = \frac{1}{\kappa} \ln z^+ + C. \tag{6}
\]

where \(\kappa\) is the von Kármán constant. Figure 2 shows that in the cases of \(Re_f = 400, 510\) and 600, the logarithmic region is not observed due to the low Reynolds numbers. In the cases of \(Re_f = 775\) and 1140, on the other hand, the logarithmic region starts to appear at \(z^+ > 30\). Present results with \(Re_f = 775\) and 1140 agree well with the experiments of Caldwell et al. [21] and with the DNS of Coleman [11].

The von Kármán constant \(\kappa\) can be obtained by

\[
\frac{1}{\kappa} = z^+ \frac{dQ^+}{dz^+}. \tag{7}
\]

The common value known for non-rotating turbulent boundary layers is \(\kappa = 0.4 – 0.42\). The obtained results are shown in Figure 3. In the cases of \(Re_f = 400, 500\) and 600, the von Kármán constant does not exhibit any constant region but increases monotonically. In the higher Reynolds number of \(Re_f = 775\), \(\kappa\) starts to exhibit constant region. With the increasing Reynolds number, \(\kappa\) exhibits a local maximum and stays nearly at a constant value in a wider region. This trend is very close to the one obtained for the turbulent Poiseuille flow shown by a gray dotted line. This indicates that, if the mean velocity is expressed in the term of \(Q\), the logarithmic nature of the mean velocity is very robust in spite of the three-dimensionality of the velocity field.

The hodographs of the mean velocities for \(Re_f = 400, 510, 600, 775\) and 1140 are given in Figure 4. The analytical solution in the laminar Ekman boundary layer is also shown. The spiral shrinks as the increase of the Reynolds number. This means that the direction of the mean flow becomes closer to that of the geostrophic wind. The
angles $\phi_{u0}$ between the shear direction at the bottom wall and the geostrophic wind direction are shown in Table 2. The analytical solution of the laminar Ekman boundary layer gives 45 degrees. However, the angle $\phi_{u0}$ in the turbulent Ekman boundary layer decreases to a smaller value of 19 – 28 degrees. Caldwell et al. [21] also obtained the smaller angles of $\phi_{u0} = 19 – 28$ in his experiments. As for the Reynolds number dependence, the angle $\phi_{u0}$ decreases with the increase of the Reynolds number. This is because the momentum transfer to the vertical direction is enhanced in the case of the higher Reynolds numbers. Therefore the momentum of the geostrophic wind penetrates more deeply into the near-wall region for the higher Reynolds numbers.

### 3.2 Turbulent intensity

Turbulent intensities are shown in Figure 5. The height $z$ is normalized by the wall-unit and $\delta_{Q_{\text{max}}}$, where $\delta_{Q_{\text{max}}}$ is the height at which $Q$ becomes maximal. In the vicinity of the wall, the velocity fluctuations of each component become larger with increasing the Reynolds number. In the upper region, on the other hand, the fluctuations are isotropic. Note that in the case of $Re_f = 1140$, the velocity fluctuations of each component at $z/\delta_{Q_{\text{max}}} > 1.5$ is smaller than those in the others Reynolds numbers. This is because the box size for $Re_f = 1140$ is smaller than the other cases. Figure 6 shows the streamwise velocity fluctuation ($u'_{\text{rms}}$) plotted against $z^*$. It becomes larger in the logarithmic region ($z^* \approx 200$) with increasing the Reynolds number. This trend is same as in turbulent channel and pipe flows. Morrison et al. [22] reported that the second maximum appeared for high Reynolds numbers.

### 3.3 Budget of Reynolds stress

For the turbulent Ekman boundary layer flows, the transport equations are given by

$$\frac{D}{Dt} u_i u_j = P_{ij} + T_{ij} + D_{ij} + C_{ij} - \varepsilon_{ij},$$

where the terms on the right-hand side are identified as follows

- production term:
  $$P_{ij} = -u_j u_k \frac{\partial U_i}{\partial x_k} - u_j u_k \frac{\partial U_j}{\partial x_k}.$$

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**Table 2** Mean shear directions at the wall.

<table>
<thead>
<tr>
<th>$Re_f$</th>
<th>400</th>
<th>510</th>
<th>600</th>
<th>775</th>
<th>1140</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\phi_{u0}$ [deg.]</td>
<td>28.7</td>
<td>25.4</td>
<td>23.3</td>
<td>21.2</td>
<td>19.4</td>
</tr>
</tbody>
</table>

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**References**

1. Caldwell et al., 1972
2. Abe et al., 2001
3. Morrison et al., 2001
turbulent diffusion term:

\[ T_{ij} = -\varepsilon \frac{\partial}{\partial x_k} u_i u_j u_k \]

velocity pressure-gradient correlation term:

\[ \Pi_{ij} = -\left( u_i \frac{\partial P}{\partial x_j} + u_j \frac{\partial P}{\partial x_i} \right) \]

molecular diffusion term:

\[ D_{ij} = \nu \frac{\partial^2}{\partial x_k^2} u_i u_j \]

Coriolis force production term:

\[ C_{ij} = -\varepsilon_{ikl} f_k u_j u_l' - \varepsilon_{ikl} f_k u_i' u_l' \]

dissipation term:

\[ \varepsilon_{ij} = -2\nu \left( \frac{\partial u_i'}{\partial x_k} \right) \left( \frac{\partial u_j'}{\partial x_k} \right) \]

where, \( \varepsilon \) in the Coriolis force production term is Eddington’s epsilon. The indices \((1, 2, 3)\) are used to denote the streamwise \((x)\), spanwise \((y)\) and wall-normal \((z)\) directions, respectively.

Figure 7 shows the terms in the budget of \( \overline{ww'} \). The black and the red lines show the terms for \( Re_f = 400 \) and \( 1140 \), respectively. The Coriolis force production term \( C_{33} \) in the budget of \( \overline{ww'} \) is equal to zero. The values of \( \Pi_{33} \), \( D_{33} \) and \( \varepsilon_{33} \) increase near the wall with the increasing Reynolds number. However, the profile of \( T_{33} \) at the low Reynolds number differs from that at the high Reynolds number. In the case of the low Reynolds number, \( T_{33} \) loses energy near the wall. On the other hand, in the case of the high Reynolds number, \( T_{33} \) gains energy. Moreover, as the Reynolds number increases, the profile of \( T_{33} \) tends to be close to that of the turbulent Poiseuille flow (Figure 8). This means that the flow field in the vicinity of the wall becomes gradually two-dimensional turbulent flow with the increasing Reynolds number. Since the term \( T_{33} \) is expressed as \(-\partial(\overline{ww'})/\partial z\), there is also a difference in the skewness factor of \( w' \), i.e., \( S(w') \). It should be noted that the profile of \( S(w') \) at \( z^+ < 5 \) in the Ekman boundary layer becomes more negative with the increasing Reynolds number (see Figure 9). This tendency does not correspond to that of the turbulent Poiseuille flow. In the fully developed Poiseuille flow, \( S(w') \) at the wall is positive (see the dotted light gray line in Figure 9). This means the so-called Q2 (ejection) event is less frequent but dominant in the \( u'w' \) coordinate of the Poiseuille flow. On the other hand, in the case of the Ekman boundary layer, Q4 (sweep) event becomes more and more dominant with increasing \( Re_f \). This is a new finding and the underlying reason is left of further study.

Figure 7 Budget of \( \overline{ww'} \) normalized by \( u_t^3/\nu \).

Figure 8 Profile of \( T_{33} \) normalized by \( u_t^3/\nu \).

Figure 9 Skewness factor \( S(w') \).

For the budget of \( \overline{\nu'w'} \), it is clear that the terms of \( T_{22} \), \( P_{22} \), \( D_{22} \) and \( \varepsilon_{22} \) are well scaled by the wall-unit (Figure 10). The profile of \( P_{22} = -2\overline{\nu'w'}/\partial z \) at the high Reynolds number, however, differ from that at the low Reynolds number as shown in Figure 11. The profile of \( P_{22} \) has two peaks at each Reynolds number. The first peak increases at \( z^+ \sim 10 \) with the increasing Reynolds number. This is because \( -\overline{\nu'w'} \) decreases at \( z^+ \sim 10 \) with the increasing Reynolds number and \( \partial w'/\partial z^+ \) varies little. On the other hand, the second peak decreases with the increasing Reynolds number. The point of the second
peak roughly corresponds to the maximum of $-\overline{vw}'$ and it’s value decreases at the high Reynolds number (Figure 13). On the contrary, $\partial V'/\partial z^*$ at the high Reynolds number decreases at that point (Figure 14). The second peak at the high Reynolds number consequently decreases. In addition, for the second peak of $P_{22}$ is well scaled by $\delta_t$, where $\delta_t (= u_t/f)$ is the turbulent depth. This indicates that $P_{22}$ is affected by the outer region. 

Figure 15 shows the budget of $\overline{vw}'$. The term of $P_{23}$ ($=-\overline{w'v'}\partial V'/\partial z$) denotes the same tendency of $P_{22}$. The first peak increases at $z^* \sim 15$ with the increasing Reynolds number, while the second peak decreases as shown in Figure 16. This is because $\overline{vw}'$ increases at $z^* \sim 10$ with the increasing Reynolds numbers while $\partial V'/\partial z^*$ varies little at that height (Figure 18). In addition, the second peak of $P_{23}$ roughly corresponds to the maximum point of the spanwise mean velocity gradient. In the case of the low Reynolds number, its gradient is larger. Thus the first peak of $P_{23}$ is larger and the second peak decreases with the increasing Reynolds number. Moreover, the second peak of $P_{23}$ is well scaled by the outer variables (Figure 17). This tendency is also seen in $P_{22}$.
4. Turbulence structure

4.1 Large-scale structure

Figure 19 shows the spanwise wavelength $\lambda_y$ of the maxima of the pre-multiplied energy spectra for each Reynolds number. It is well known that the wavelength at the peak of the pre-multiplied energy spectrum indicates that of the mainly energy-containing scale (MES). In the vicinity of the wall, the spanwise wavelength of MES is $\lambda_y/\delta_e \approx 100$. This corresponds to the streaky structures near the wall. In the mid-height region ($z/D < 6$), the length scales increase linearly with the increasing height. In the upper region ($6 < z/D < 15$), however, the wavelengths of MES stay at a constant value of $\lambda_y/D \approx 15$–20. This suggests the existence of the large-scale structures which can be scaled spanwisely by the viscous Ekman layer depth $D$. In the former study, Shingai et al. [14] suggested the spanwise wavelength of MES can be scaled by $\delta Q_{max}$. The present study, however, indicates that the scaling by the viscous Ekman layer depth gives a better collapse.

A $y-z$ plane view of an instantaneous flow field at each Reynolds number is visualized in Figure 20. The contours show the strength of the instantaneous streamwise velocity fluctuations $u'$. The red and the blue regions represent the high- and low-speed regions, respectively. In the near-wall region, the small-scale structures are observed, while the scale of structures increases linearly with the increasing height. This result is in accordance with that of Figure 19. These figures also indicate that the structures of about $15D-20D$ scale exist at $z/D \approx 6$ for each Reynolds number. It should be noted that these large-scale structures incline toward the $y$-direction. Since these structures are not observed in the channel flow, it is a particular structure of the Ekman boundary layer.

To grasp the three-dimensional characteristics of the turbulence structures, a bird’s eye view of an instantaneous flow field for $Re_f = 1393$ is displayed in Figure 21. Figure 22 is an enlarged view of a part of Figure 21 from a different viewpoint. The isosurfaces, colored red and blue, show the high ($u' > 3.0$)- and low ($u' < -3.0$)-speed regions, respectively. The green isosurfaces show the low-speed regions ($u' < -1.2$) at $z/D > 5$. The streaky structures are observed near the wall and elongated along the mean velocity direction. On the other hand, large low-speed regions exist in the upper region. The large-scale structures rise up from the bottom because the low-speed fluid is conveyed from the bottom wall. The structures are not aligned in the direction of the mean velocity. They are elongated approximately in the direction of the geostrophic wind (in the $x$-direction) and are also inclined slightly toward the higher pressure side (in the minus $y$-
4.2 Material line

To examine the large-scale structure circumstantially, the motions of passive material lines in the turbulent Ekman boundary layer are visualized. Batchelor [23], Kida et al. [24] and Goto et al. [25] studied material lines in turbulent flows. They focused mainly upon the stretching rates of material lines.

The material line is represented by a chain which consists of fluid particles. An arbitrary point on the material line is advected by the local velocity as

$$\frac{dx_p(t)}{dt} = u(x_p(t), y_p(t)).$$

(9)

where the suffix $p$ is an index of the particles. The term on the right-hand side of equation (9) is calculated by linear interpolation in terms of the velocity field at the grid points. The perfect elastic collision condition is adopted on the bottom wall. Although the same condition is assumed to the top boundary condition, no particle has reached the top boundary. The segments of the material line are generally elongated as time elapses. Whenever the distance between the adjacent two particles reaches a half of the spanwise grid spacing $\Delta z$, a new particle is inserted at the center between the two particles. The maximal total number of particles is limited due to the computational resource.

In order to evaluate an effect of the initial distance from the wall, the material lines are released at $z^* = 17$ ($z/D = 0.65$) and $z^* = 152$ ($z/D = 5.85$) (see Figure 23(a)). The length of each material line is the half of the spanwise box size. Snapshots of the material lines at four time instants for $Re_f = 400$ are drawn in Figure 23. In the vicinity of the wall, the material line becomes wavy and is elongated toward the lower pressure with time. This corresponds to
Fig. 23 Motions of material line for $Re_f = 400$. $a'–d'$ are the top views, while $a–d$ are the side views seen from the left of $a'–d'$. The color indicates the height from the bottom wall blue to red, $z^+ = 0$ to $z^+ = 182$ ($z/D = 7$). (a, $a'$) $t^* = 0$, (b, $b'$) $t^* = 54$, (c, $c'$) $t^* = 108$, (d, $d'$) $t^* = 162$. 
the streaky structure in Figure 21. A strong ejection event is observed in the oval A in Figure 23. If we compare between the advected spanwise distance for the material line raised up to the outer region and the one staying in the vicinity of the wall, the distance of the former one is smaller than that of the latter. This is because the spanwise mean velocity $V$ is larger in the vicinity of the wall than in the outer region. In fact, the spanwise movement of the material line near the wall in the oval A is roughly equal to the product of the spanwise mean velocity $V$ and the elapsed time $t^*$. Therefore, the inclination of the large-scale structure as described in the previous sub-section is caused by the combination of the strong ejection and the three-dimensional mean velocity profile.

5. Eddy-viscosity model

Many theoretical approaches to the turbulent Ekman problem have employed some empirical specification for the eddy-viscosity. Among them, we will examine a mixing length model proposed by Blackadar [15, 16] in comparison with the present DNS data. The eddy-viscosity coefficient is generally defined by

$$-ar{w} \overline{u} = K_m \frac{dU}{dz}, \quad -\overline{v} \overline{w} = K_m \frac{dV}{dz}. \quad (10)$$

In the mixing length representation, the eddy-viscosity is expressed as

$$K_m = l^2 S \quad (11)$$

where $l$ is the mixing length defined later and $S$ the magnitude of the wind shear

$$S = \left\{ \left( \frac{dU}{dz} \right)^2 + \left( \frac{dV}{dz} \right)^2 \right\}^{1/2}. \quad (12)$$

The mixing length $l$ in equation (11) is assumed to have a form

$$\frac{1}{l} = \frac{1}{kz} + \frac{1}{\lambda}. \quad (13)$$

Here, $\lambda$ is an empirical parameter which specifies a maximum value of $l$ as $z$ approaches infinity. Blackadar [15] first used the following empirical relation for $\lambda$:

$$\lambda = 2.7 \times 10^{-4} \frac{G}{f}, \quad (14)$$

while in his later paper [16] he used the relation

$$\lambda = u_\tau \frac{H}{f}, \quad (15)$$

where $H$ is the boundary layer thickness and $u_\tau$ the friction velocity. We used equation (15) for $\lambda$ to compare with our DNS data and calculated $u_\tau$ and $H$ from DNS data. Here, $H$ is assumed the height at which the wind direction becomes first parallel to the geostrophic wind direction.

For the case of a steady state $\left( \partial \overline{u} / \partial t = 0 \right)$ and horizontally homogeneous state $\left( \partial \overline{u} / \partial x = 0, \quad \partial \overline{u} / \partial y = 0 \right)$, the Navier-Stokes equation (3) with the assumed eddy-viscosity model of equation (11) can be expressed as

$$\frac{d}{dz} \left( (v + K_m) \frac{dU}{dz} \right) = -fv, \quad (16)$$

$$\frac{d}{dz} \left( (v + K_m) \frac{dV}{dz} \right) = -f(U - G), \quad (17)$$

These equations were solved numerically. The bottom and top boundary conditions are $U = 0$, $V = 0$ and $U = G$, $V = 0$, respectively. Figure 24 shows the eddy-viscosity profiles. The dashed lines show the results by the

![Fig. 24 Eddy-viscosity profiles.](image-url)
Blackadar’s model. The solid lines show the viscosity profiles derived from mean velocity profiles of our DNS. The eddy viscosity derived from our DNS data is calculated by the formula:

\[ K_m(z) = \left( \tau_x^2 + \tau_y^2 \right)^{1/2} \left( \frac{dU}{dz} \right)^2 + \left( \frac{dV}{dz} \right)^2 \right]^{-1/2}. \]  

(18)

The calculation of \( K_m \) requires the mean velocity gradients. The Blackadar’s model does not agree with DNS data at all the Reynolds numbers tested. In the vicinity of the wall, the results of the Blackadar’s model are larger than our results. This is because the effect of viscosity is not considered in equation (13). In the rest of the part, the eddy-viscosity profiles using Blackadar’s model are smaller. The mixing length profiles are shown in Figure 25 and compared with the experiments of Caldwell et al. [21]. The mixing length can be computed by applying the following definition:

\[ l(z) = \left( \tau_x^2 + \tau_y^2 \right)^{1/4} \left( \frac{dU}{dz} \right)^2 + \left( \frac{dV}{dz} \right)^2 \right]^{-1/2}. \]  

(19)

The mixing lengths by the experiment and the DNS agree almost well with each other. A discrepancy increases with the increasing height. This is because the mean velocity gradients become smaller at the larger height, thus the derivation of \( l \) becomes less accurate in the experiment. The Blackadar’s model does not agree with our DNS data for all the calculated Reynolds numbers in spite that the accurate magnitude \( S \) of the wind shear is used for the model, too. To reduce the discrepancy, we will introduce the viscous effect in the near wall region and will accommodate an empirical parameter \( \lambda \) relevant to the upper region. The van Driest damping function is employed to express the viscous effect while in the upper region the mixing length is assumed to be proportional to the viscous Ekman depth \( D \). Accordingly, a newly defined \( l \) and \( \lambda \) becomes

\[ \frac{1}{l} = \frac{1}{\kappa z \left( 1 - \exp(-z^+/\Lambda^+) \right)} + \frac{1}{\lambda}. \]  

(20)

\[ \lambda = C_\lambda D, \]  

(21)

where \( \Lambda^+ \) and \( C_\lambda \) are model constants. In this paper, these model constants are set to be \( A^+ = 26 \left( 1 + (290/Re_f)^2 \right) \) and \( C_\lambda = 2.0 \). The results of the present model are shown in Figures 24 and 25 by the dotted-and-dashed lines. The present model is in better agreement with our DNS data than the Blackadar’s one. The mean velocity profiles calculated from the Blackadar’s model and the present one are compared in Figures 26 and 27 with the DNS data. The present model predicts the mean velocity profiles give a much better agreement with the DNS data. Table 3 shows the angle \( \phi_{u0} \) and \( u_\tau \) calculated from DNS, the Blackadar’s and the present models. The Blackadar theory doesn’t predict both \( \phi_{u0} \) and \( u_\tau \). On the other hand, the present model gives very close values to those of the DNS data.

6. Conclusion

We have performed direct numerical simulations of the turbulent Ekman boundary layer over a smooth surface. The Reynolds numbers \( Re_f \) were 400, 510, 600, 775, 1140 and 1393 in order to investigate Reynolds number dependence. The three-dimensional characteristics in the turbulent Ekman boundary layer flow were studied. In addition, we evaluated the existing eddy-viscosity model [15, 16], and proposed an improved modeling. The derived conclusions are as follows:

1. The logarithmic region appears more clearly in the

![Fig. 25 Mixing length profiles.](image-url)
higher Reynolds number cases of $Re_f = 775$ and 1140. The results of $Re_f = 775$ and 1140 agree well with the results of experiment by Caldwell et al.. In the higher Reynolds numbers of $Re_f = 775$ and 1140, the von Kármán constant $\kappa$ starts to exhibit a constant region. Moreover, with increasing the Reynolds number, $\kappa$ exhibits a local maximum and nearly stays nearly at a constant value in a wider region.

2. The Reynolds number dependence of the terms of $T_{33}$, $P_{22}$ and $P_{23}$ is significant. The turbulent diffusion $T_{33}$ at the high Reynolds number tends to be close to the profile of the Poiseuille flow in the vicinity of the wall. This means that the flow field near the wall becomes gradually two-dimensional with the increasing Reynolds number. However, the profiles of the skewness factor $S(w')$ at high Reynolds number differ from that of the Poiseuille flow. The profile of $S(w')$ at $z^+ < 5$ in the Ekman boundary layer becomes more negative with the increasing Reynolds number. This means the sweep event becomes more dominant in the Ekman boundary layer.

3. The analysis using the pre-multiplied energy spectra and instantaneous flow fields in $y-z$ plane indicates that the large-scale structures with a spanwise scale of $15D$–$20D$ exist in the upper region ($z/D \sim 6$). In addition, it is found that the low-speed large-scale structures are not aligned in the direction of the mean velocity. They are elongated approximately in the direction of the geostrophic wind and also slightly toward the higher pressure side. The motion of material lines reveals the mechanism of the inclination of the large-scale structures. That is, the inclination of the large-scale structure is caused by the combination of the strong ejection event and the three-dimensional mean velocity profile.

4. The existing model does not show good agreement with our DNS data. An improvement is proposed to the expression of the mixing length. The mean velocity profiles calculated from our improved model well agree with our DNS data.

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